

# MechGenius Creations



The Yellow Floating Heart is an invasive aquatic plant that threatens local waterways by spreading quickly and disrupting native ecosystems.

## BACKGROUND

- LNVA manages hundreds of miles of waterways.
- Yellow Floating Heart spreads quickly, covering 20–30% of infested areas.
- Can reduce water flow by up to 60%.
- Removal costs \$500–\$2,000 per acre yearly.
- Early detection is limited and inefficient.



### APPROACH

Develop an AI model to detect Yellow Floating Heart and distinguish it from similar local plant species.



### PROTOTYPE

Built and tested using local aquatic plant datasets.

## FIELD DATA COLLECTION & VERIFICATION

Local field imagery and structured datasets were used to compare species and support model validation.



### FIELD DATA COLLECTION

Date Collected:  
4/3/26 – Canal Site  
SW of Winnie, TX

- Site data collection in local waterways
- Species comparison between invasive and non-invasive aquatic plants
- Image dataset support for training and validation
- Verification methods to confirm model reliability



### LOCAL DATA COLLECTED

110 images collected	3 datasets used	6 plant species represented	JPEG image format	45 total trials completed
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### ACTIVE INFESTATION SAMPLES

Giant Salvinia	Oenothera speciosa
Plant classification: Invasive	Plant classification: Non-invasive
Aquatic impact: Disrupts ecosystems	Aquatic impact: Limited disruption
Ecological concern: Rapid spread and surface coverage	Ecological note: Useful comparison species



### VERIFICATION SUPPORT

Average Accuracy	Average Process Time	Average Confidence Score
<b>77.67%</b>	<b>0.021 s</b>	<b>90.06%</b>
Giant Salvinia <b>87.67%</b>	Oenothera speciosa <b>97.75%</b>	Yellow Floating Heart <b>81.17%</b>

Validation across multiple datasets helped confirm the model's ability to distinguish invasive and non-invasive species.

References / Image Credits | Invasive plant photos courtesy of Adolfo.

## Model Evaluation and Design Verification

Evaluating model performance, validation results, and workflow reliability.



45 Trials



3 Datasets



6 Plant Species

Validation was completed using local aquatic plant datasets and multiple test runs.

### Test Results Summary

Metric	Yellow Floating Heart	Spatterdock
Average Accuracy	79.82%	89.91%
Average Process Time (s)	0.032	
Average Confidence Score		
Accuracy	88.57%	81.82%
Recall/Sensitivity	90.91%	85.00%
Specificity	89.17%	80.43%
Precision	65.90%	65.00%

Full results available; Yellow Floating Heart and Spatterdock shown as primary targets.

### Model Evaluation

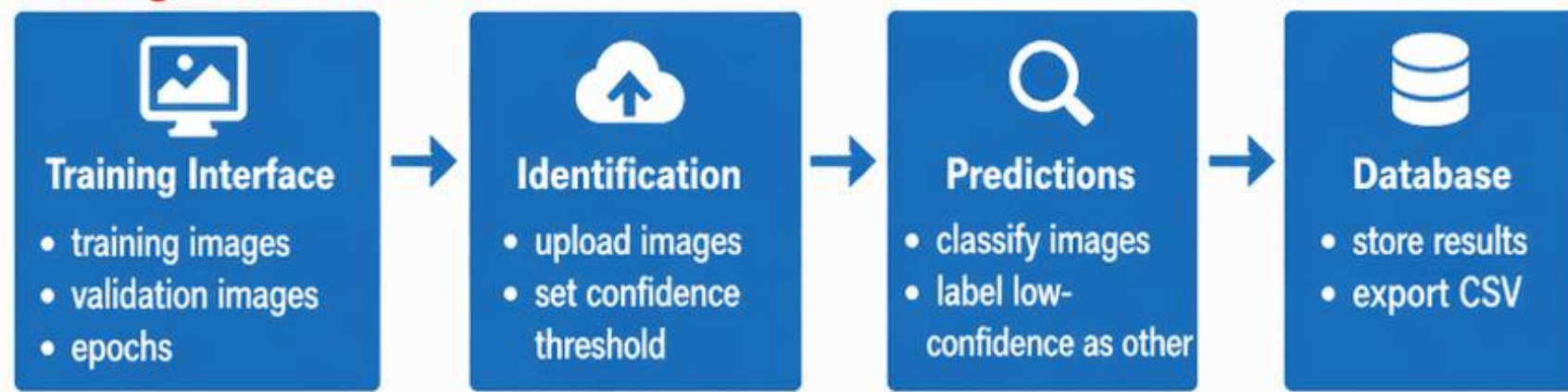
- **Accuracy** = overall correctness of predictions
- **Precision** = ratio of true positives to predicted positives
- **Recall** = ratio of true positives to actual positives
- **Specificity** = ability to correctly reject negatives

**Confusion Matrix**

		Predicted Class	
		Positive	Negative
Actual Class	Positive	True Positive (TP)	False Positive (FP)
	Negative	False Negative (FN)	True Negative (TN)

Legend: Accuracy (Green), Precision (Orange), Recall (Sensitivity) (Red), Specificity (Blue)

### Design Verification



- ✓ Verified across multiple datasets
- ✓ Supports invasive and non-invasive species distinction
- ✓ Repeated runs confirmed consistent performance
- ✓ Suitable for field-based identification support

Sources: Local test results, system workflow, and evaluation methods compiled from project development materials.

## FINAL SYSTEM EVALUATION & FUTURE WORK

Key outcomes, GIS integration potential, and next development steps.



### FINAL SYSTEM EVALUATION

- Achieved 79.82% overall accuracy
- Successfully identified invasive plant species from image data
- System runs locally and can operate offline
- Built as a scalable prototype for future expansion



Plant Identification



GIS Mapping Potential



Scalable Local Build



### GIS MAPPING INTEGRATION



- AI detections can be applied to drone mapping imagery
- Orthomosaic layers can be created in ArcGIS
- Approximate GSD: 3 cm/px
- New GIS layers can be compared over time to monitor invasive plant growth

#### SAMPLE MISSION PARAMETERS

Altitude: 200 ft	Overlap: 70%	Camera angle: 90°	Speed: 11 - 12 mph
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### FUTURE WORK

1. Expand dataset size and field data
2. Improve the user interface and automate training
3. Integrate the AI model with GIS mapping workflows
4. Explore autonomous detection and removal strategies

Based on project evaluation, GIS mapping studies, and future system concepts.

## AI Detection System Development

The detection system was built using an open-source PyTorch workflow and organized into three core stages: training, identification, and analysis.



### Model Build

- Open-source PyTorch framework
- Runs on a local computer or through Streamlit
- Coding support from Copilot and Qwen AI
- Available on GitHub for development and testing



Compared with Google AI Studio, the PyTorch build offers more flexibility, public access, and scalability for local dataset growth.

### System Workflow

- 1 Train**  
Screenshot of the training interface showing species selection and training parameters.
- 2 Identify**  
Screenshot of the identification interface showing image upload and confidence threshold settings.
- 3 Analyze**  
Screenshot of the analysis interface showing a table of detection records with columns for Run ID, Image Name, Species, Invs, Score, and Time.

**Workflow Output:** The final system supports model training, image-based identification, and detection record analysis in one interface.



**GITHUB FOR AI MODEL**



**SCAN FOR MORE**

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